

# Jop-Shop Scheduling

*How to solve a Jop-shop scheduling problem with Genetic Algorithms?*

Rick van Aalst, 20236338

# Content

- Description
- Problem Definition
- Objective and Conditions
- Operators (GA)
- Algorithm Setup
- Results
- Conclusions and Limitations

# What is Job-Shop Scheduling?

- **Job Shop Scheduling:** In manufacturing or production environments, genetic algorithms can be used to optimize the scheduling of jobs on machines, considering constraints such as processing times, machine availability, and precedence relationships between tasks.
- Genetic algorithms can be applied to find an optimal or near-optimal schedule for more complex instances of the Job Shop Scheduling problem, considering additional factors such as machine constraints, job priorities, and setup times between operations.

Survey on Shop-Scheduling methods

**GENETIC ALGORITHMS FOR SHOP SCHEDULING  
PROBLEMS: A SURVEY**

*Frank Werner\**

Otto-von-Guericke-Universität, Fakultät für Mathematik, 39106 Magdeburg, Germany

# What is Shop Scheduling?

- A set of  $n$  jobs ( $J_1, J_2, J_3, \dots, J_n$ ) which are processed on  
A set of  $m$  machines ( $M_1, M_2, M_3, \dots, M_m$ )
- The processing of a job  $J_i$  on a particular machine  $M_j$  is denoted as an operation and noted by  $(i, j)$
- Each job  $J_i$  consists of a number  $n_i$  of operations
- For the deterministic scheduling problems, the processing time  $p_{ij}$  of each operation  $(i, j)$  is given in advance

# Problem Definition

- For describing these problems, there exists three classifications:
  - $\alpha$  (Machine Environment, e.g. Flow Shop, Jop-shop etc.)
  - $\beta$  (Job characteristics, e.g. release dates, due dates, and weights etc.)
  - $\gamma$  (Optimization Criterion, e.g. minimize- total makespan and maximized lateness etc.)
- According to the restrictions on the technological routes of the jobs, we distinguish a **flow shop**, a **job shop** and an **open shop**

# Problem Definition (Shops)

- Flow Shop ( $\alpha = \mathbf{F}$ )
  - Each job  $J_i$  has exactly  $m$  operations
  - Same route
  - Assumption:  $M_1 \rightarrow M_2 \rightarrow M_3 \rightarrow \dots \rightarrow M_m$
- Job Shop ( $\alpha = \mathbf{J}$ )
  - A specific route for each job
    - $M_{j_1} \rightarrow M_{j_2} \rightarrow M_{j_3} \rightarrow \dots \rightarrow M_{j_{n_i}}$  for each job  $J_i$  ( $1 < i < n$ )
  - Number of operations smaller, equal or larger than  $m$ 
    - Different notation:  $(i, j, k) \rightarrow k_{th}$  processing of job  $J_i$  on machine  $M_j$
- Open Shop ( $\alpha = \mathbf{O}$ )
  - No routes for jobs
  - Assumed every job has to be processed on every machine
- There exists Generalizations on these shops such as mixed- and general shop
- There exists extensions to shops: **hybrid or flexible shops**
  - Multi-stage and parallel problems

# Problem Definition (Constraints)

- For any job  $J_i$  there might be a release date  $r_i$ , a due date  $d_i$  and/or a weight  $w_i$
- Other constraints such as no waiting times between operations of a job ( $\beta = \text{no wait}$ ), sequence-(in)dependant set-up times between processing of operations



# Problem Definition (Optimality criterion)

- $\gamma$  indicates optimality criterion
- Minimization of makespan  $C_{\max}$
- Minimization of sum of weighted completion time  $\sum w_i C_i$
- Minimization of sum of weighted tardiness  $\sum w_i T_i$
- Or problems without weights ( $w_i = 1$ )

# Feasible Solutions

- Specify Job orders on the machines
  - Job Sequence
  - Combining routes and job orders into rank matrix  $R$  where  $r_{ij}$  denotes the rank of operation (i, j)
- Example Matrix ( $n \times m$ ):

$$R = \begin{pmatrix} 4 & 3 & 2 & 1 \\ 2 & 4 & 1 & 5 \\ 1 & 5 & 3 & 4 \end{pmatrix}$$

$$\begin{aligned} M_1 : & J_3 \rightarrow J_2 \rightarrow J_1 \\ M_2 : & J_1 \rightarrow J_2 \rightarrow J_3 \\ M_3 : & J_2 \rightarrow J_1 \rightarrow J_3 \\ M_4 : & J_1 \rightarrow J_3 \rightarrow J_2 \end{aligned}$$

$$\begin{aligned} J_1 : & M_4 \rightarrow M_3 \rightarrow M_2 \rightarrow M_1 \\ J_2 : & M_3 \rightarrow M_1 \rightarrow M_2 \rightarrow M_4 \\ J_3 : & M_1 \rightarrow M_3 \rightarrow M_4 \rightarrow M_2 \end{aligned}$$

# Genetic Algorithms

- Representation:
  - Not clear representation, depends on problem
  - Several encoding strategies exists

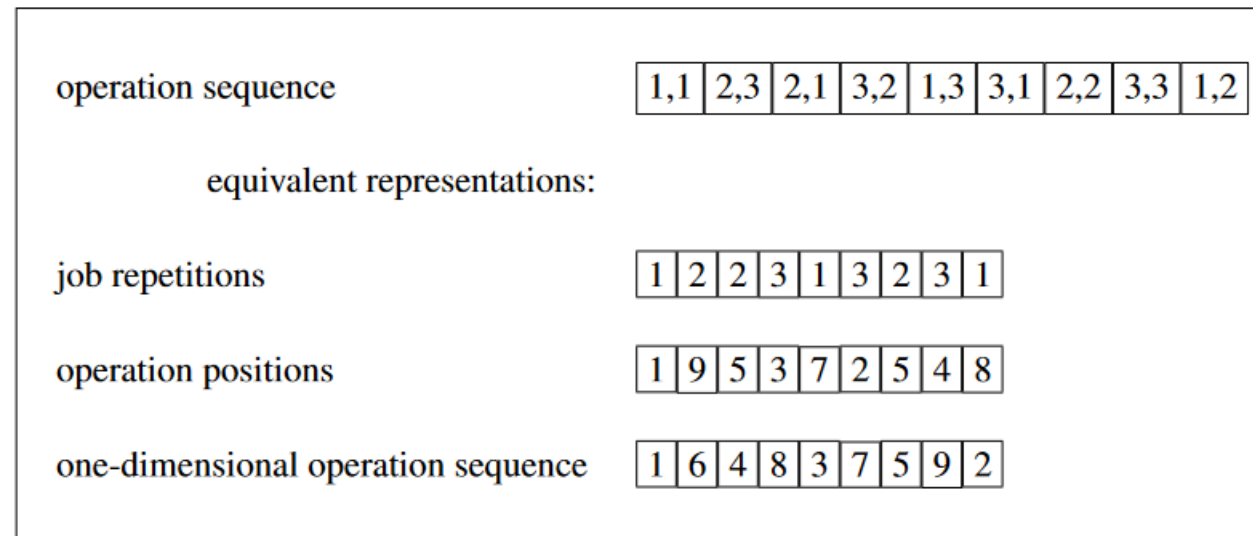


Figure 1. Operation-based representation

# Operation-based

- Each job consists  $m$  operations, so each chromosome has  $nm$  length (each gene represents operation  $(i, j)$ )
- Several variations of representations

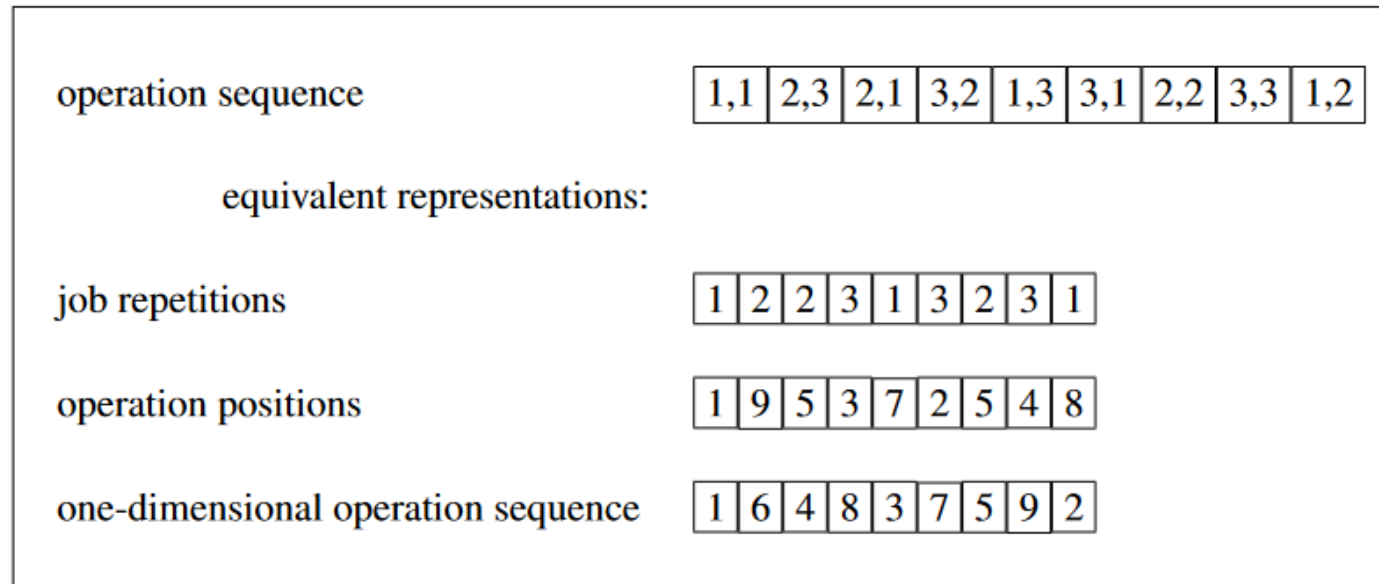


Figure 1. Operation-based representation

# Operation-based

- Job repetitions
  - Each gene contains a job index  $i$
  - Repeats  $m$  times for a given route

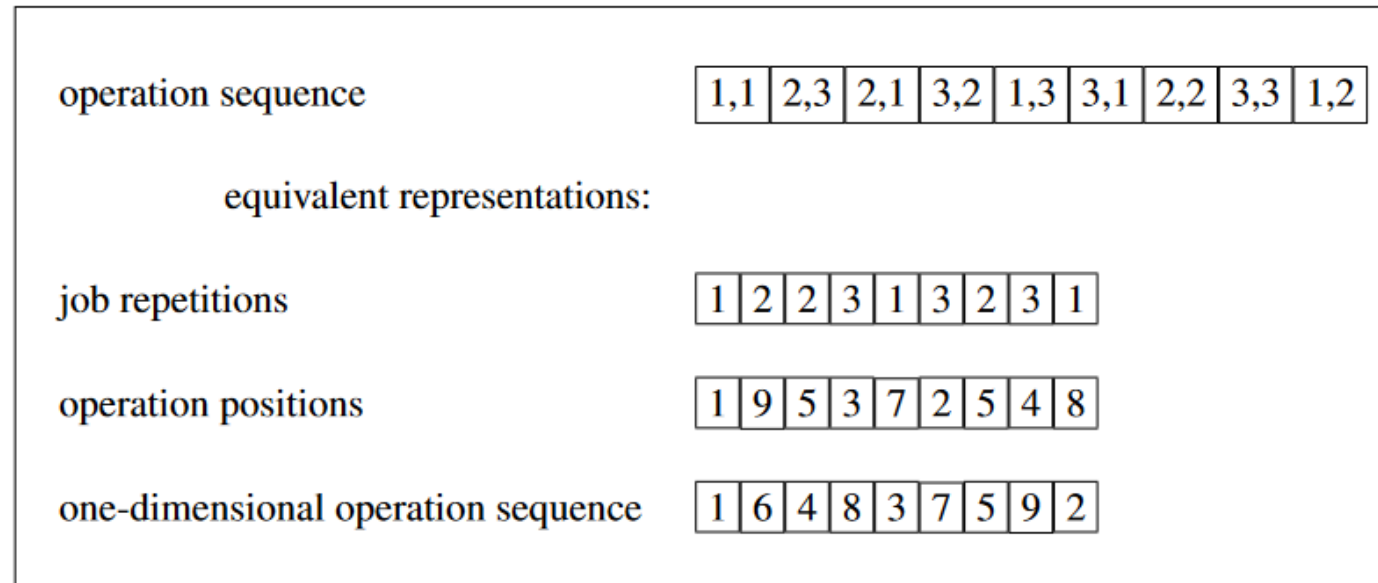


Figure 1. Operation-based representation

# Operation-based

- Operation Positions

- Subsequent numbering

- (1,1), (1,2), (1,3), (2,1), (2,2), (2,3), (3,1), (3,2), (3,3)

- E.g. number 5 at gene 3 represents (1,3) at position 5

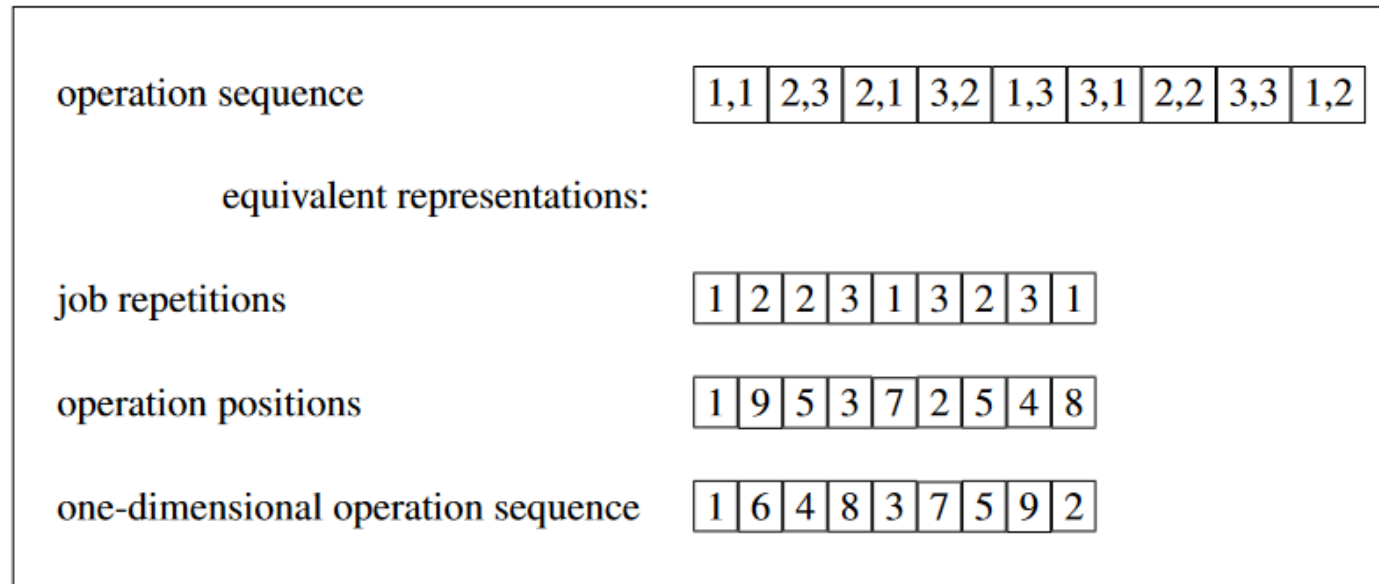


Figure 1. Operation-based representation

# Algorithm

## A Genetic Algorithm Applicable to Large-Scale Job-Shop Problems

Takeshi Yamada and Ryohei Nakano

NTT Communication Science Laboratories, 2 Hikaridai, Seika-cho, Soraku-gun, Kyoto, 619-02, Japan

- GA-GT Algorithm
- Active schedules (parents) to create new job-schedules (offspring)
- Griffier & Thompson (GT) algorithm + uniform crossover
- Optimal solutions for 10 x 10 (n jobs x m machines)
- Good solutions for 20 x 20

# Algorithm

- Minimization Makespan
- The processing of job  $J_j$  On machine  $M_r$

Is the operation  $O_{j, i, r}$

Where  $i \in \{1, \dots, m\}$  is the position of operation in the technological sequence with processing time  $p_{j, i, r}$

- The objective is to determine the set of completion times for each operation for each operation  $c_{j, i, r}$  which minimizes makespan  $S_{\max}$

Table 1  
A  $6 \times 6$  job-shop problem

Job	Operation routing (processing time)					
1	3(1)	1(3)	2(6)	4(7)	6(3)	5(6)
2	2(8)	3(5)	5(10)	6(10)	1(10)	4(4)
3	3(5)	4(4)	6(8)	1(9)	2(1)	5(7)
4	2(5)	1(5)	3(5)	4(3)	5(8)	6(9)
5	3(9)	2(3)	5(5)	6(4)	1(3)	4(1)
6	2(3)	4(3)	6(9)	1(10)	5(4)	3(1)

Reprinted from reference [11], pp. 226.



# Algorithm

- Gantt-Chart

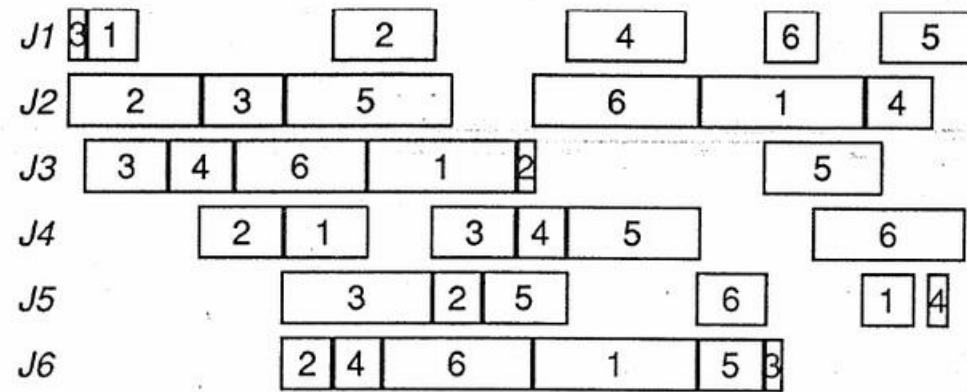


Figure 1. Gantt chart of a solution to the  $6 \times 6$  job-shop problem

Table 2

Optimal solution to the  $6 \times 6$  job-shop problem

Job	Completion times					
1	1	4	22	37	45	55
2	8	13	23	38	48	52
3	6	10	18	27	28	49
4	13	18	27	30	38	54
5	22	25	30	42	51	53
6	16	19	28	38	42	43

# Algorithm

- Consider Temporal order
- A set  $C$  of the earliest operations in technological sequence among operations which are not yet scheduled is defined (cut)
- The earliest possible completion time  $EC_{j,i}$  is calculated for each operation  $O_{j,i} \in C$

- (A1) Find  $O_{j^*,i^*,r^*}$  which has a minimum<sup>2</sup>  $EC$  in  $C$ :  $EC_{j^*,i^*} = \min\{EC_{j,i} \mid O_{j,i} \in C\}$   
 Specify  $G$ : a set of operations which consists of  $O_{j,i,r^*} \in C$  sharing the same machine  $M_{r^*}$  with  $O_{j^*,i^*,r^*}$  and the processing of  $O_{j,i,r^*}$  and  $O_{j^*,i^*,r^*}$  overlaps.  $G$  is called a *conflict set*.
- (A2) Choose one of the operations  $O_{j_s,i_s}$  from  $G$ , and schedule  $O_{j_s,i_s}$  according to  $EC_{j_s,i_s}$ .
- (A3) Update  $C$  and  $EC$ s.

Repeat Step (A1) ~ Step (A3), until all operations are scheduled, and then an active schedule is obtained.

In Step (A2), if all possible choices are considered, active schedules are generated for all<sup>3</sup>.

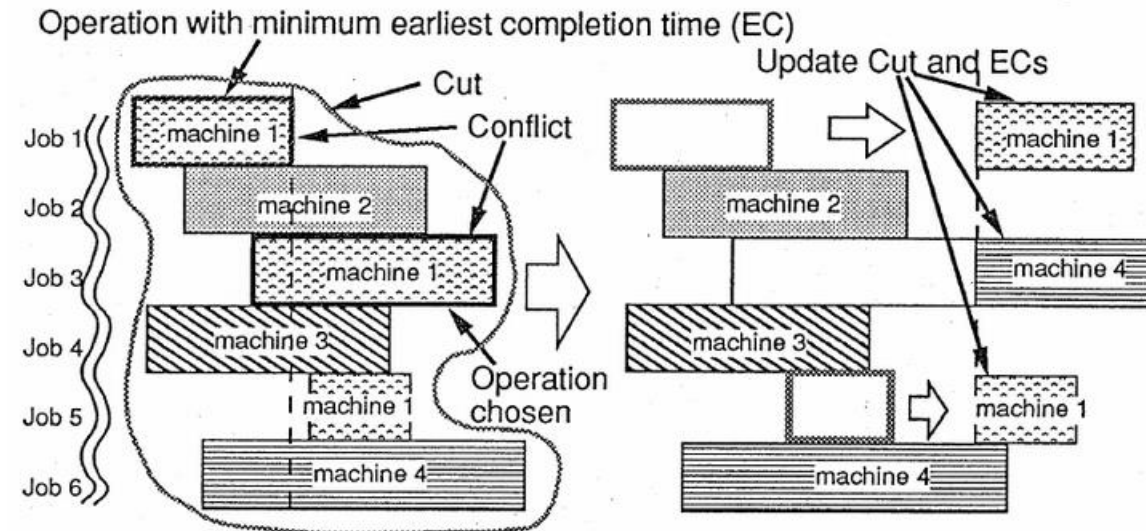


Figure 2. Giffler & Thompson's algorithm

# Representation

- Each individual  $psn$  represents an active schedule directly using elements  $\{psn_{j,i,r}\}$ 
  - $psn_{j,i,r} = c_{j,i,r}$

The makespan  $S_{psn}$  of the schedule represented by the individual  $psn$  is calculated as follows:

$$S_{psn} = \max\{psn_{j,i} \mid 1 \leq j \leq n, i = m\} \quad (1)$$

# Crossover

(C1) Do Step (A1) of the GT algorithm, obtain  $C$ ,  $ECs$  and  $G$ .

(C2) Choose one of the operations to be scheduled next from  $G$  as follows:

(a) generate a random number  $\epsilon \in [0, 1)$  and compare it with  $R_\mu \in [0, 1)$  which is a predefined constant called the *mutation rate*.

**if** ( $\epsilon < R_\mu$ ) **then** choose any operation  $O_{j_s, i_s}$  from  $G$  (mutation occurs).

(b) **otherwise** select either *mom* or *dad* with an equal probability  $1/2$ .

*Mom is assumed to be selected.*

Find an operation  $O_{j_s, i_s}$  which was scheduled earliest in *mom* among all the operations in  $G$ :

$$mom_{j_s, i_s} = \min\{mom_{j, i} \mid O_{j, i} \in G\} \quad (2)$$

(c) schedule  $O_{j_s, i_s}$  according to  $EC_{j_s, i_s}$ , then set  $kid_{j_s, i_s} = EC_{j_s, i_s}$ .

(C3) Update  $C$  and  $ECs$ .

By repeating Step (C1) ~ Step (C3) until all operations are scheduled, the new individual *kid* is obtained.

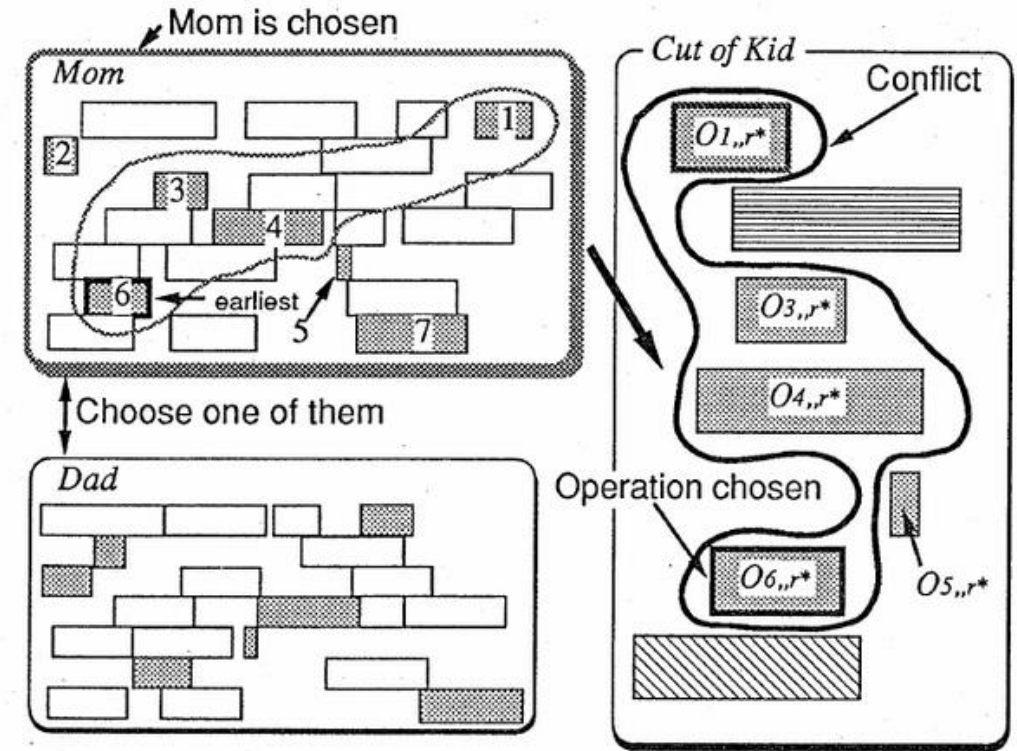


Figure 3. GA/GT crossover

# Results

Table 3  
Muth & Thompson's benchmark

Papers	6×6	10×10	20×5
Balas (1969)	55	1177	1231
McMahon (1975)	55	972	1165
Barker (1985)	55	960	1303
Adams (1988)	55	930	1178
Carlier (1989)	55	930	1165
Nakano (1991)	55	965	1215
Yamada (1992)	55	930	1184
Optimal	55	930	1165
Lower Bound	52	880	1164

Table 4  
GA/GT v.s Random Samplings

20×20 problems No.	Random		GA/GT	
	Average	Best	Average	Best
1	1356.8	1126	979	967
2	1318.6	1104	953	945
3	1313.5	1107	957	951
4	1414.3	1202	1060	1052

# Results

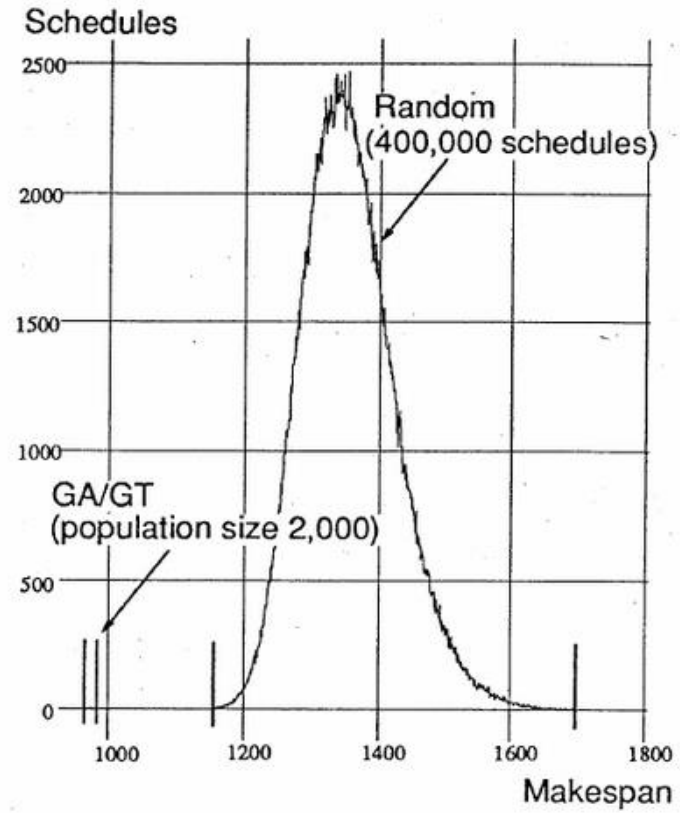


Figure 5. GA/GT v.s. Random Samplings

# Limitations

- Missing code (complexity of Job-shop with constraints and feasibility)
  - Tried to compare many representations and algorithms setup by survey but spented too much time on researching it
- In survey, diversity-operators were not considered at all